

CRX-25iA



Max. load capacity
at wrist: 25/30 kg



Max. reach
(end of flange):
1889 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | ****Reach (mm) | Controlled axes | ***Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | **Maximum speed (°/s) | | ****Allowable Wrist Load | | | Protection | | |
|--------|---------|------|----------------------------------|----------------|-----------------|-----------------------|------------------------|------------------|-----|-----|-----|-----|-----|-----------------------------|--------------------------|--------------------------|--------------------|--------------------|--------------------------|---------------|----------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | Collaborative Mode [mm/sec] | High Speed Mode [mm/sec] | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Input power source (VAC) | Body standard | Wrist & J3 arm |
| CRX | iA | 25 | 25 30 | 1889 1756* | 6 | ± 0.05 | 135 | 360 | 360 | 540 | 380 | 360 | 450 | 1000 | 2000 | 100.0/ 4.7 | 74.0/ 4.00 | 32.0/ 2.00 | 100-120 200-240 | IP67 | IP67 |

● standard ○ on request - not available *Operating space is restricted when 30kg payload mode is selected **Please set motion speed according to risk assessment of system. ***Based on ISO9283 ****Nm/Kg.m² *****At the end of flange

CRX-25iA Standard model



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