

M-20iD/35



Max. load capacity
at wrist: 35 kg



Max. reach:
1831 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | Moments (N-m)/Inertia (kg-m ²) | | | Average Power consumption (kW) | Protection | |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|-----|---------------------|-----|-----|-----|-----|-----|--|-------------------|-------------------|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | J4 Moment/Inertia | J5 Moment/Inertia | J6 Moment/Inertia | | Body standard/optional | Wrist & J3 arm standard/optional |
| M-20 | iD | 35 | 35 | 1831 | 6 | ±0.03** | 250 | 340 (370) | 260 | 458 | 400 | 360 | 900 | 180 | 180 | 200 | 350 | 350 | 400 | 110/4 | 110/4 | 60/1.5 | 1 | IP54/ IP65 | IP67 |

● standard ○ on request - not available ** Based on ISO9283

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Hollow Wrist



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