

M-1*i*A/0.5SL



Max. load capacity
at wrist: 0.5 kg



Max. reach:
420 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Average Power consumption (kW) | Protection | |
|--------|---------|-------|----------------------------------|------------|-----------------|--------------------|------------------------|----------------------------|----|-----|----|----|----|---------------------|----|----|----|-----|------|--------------------|--------------------|--------------------|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | | | | | Body standard/optional | Wrist & J3 arm standard/optional |
| M-1 | iA | 0.5SL | 0.5(1) | 420 | 4 | ± 0.03 | 23 ^{*2)} | ∅ 420 X 150 ^{*3)} | | 720 | - | - | - | 3000 | | | | 0.2 | IP20 | IP20 | | | | | |

● standard ○ on request - not available *2) with stand () with hardware and/or software option *3) ∅ in mm by height in mm *4) refer to the wrist load diagram

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4-axis, long arm



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