

# CR-4iA



Max. load capacity at wrist: 4 kg



Max. reach: 550 mm

# FANUC

Robot			Max. load capacity at wrist (kg)	Reach (mm)	Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						J4 Moment/Inertia	J5 Moment/Inertia	J6 Moment/Inertia	Average Power consumption (kW)	Protection	
Series	Version	Type						J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6					Body standard	Wrist & J3 arm
CR	iA	4	4	550	6	±0.01**	48	340/ 360***	150	354	380	200	720	500*	500*	500*	500*	500*	500*	8.86/ 2	8.86/ 2	4.9/ .67	0.5	IP67	IP67

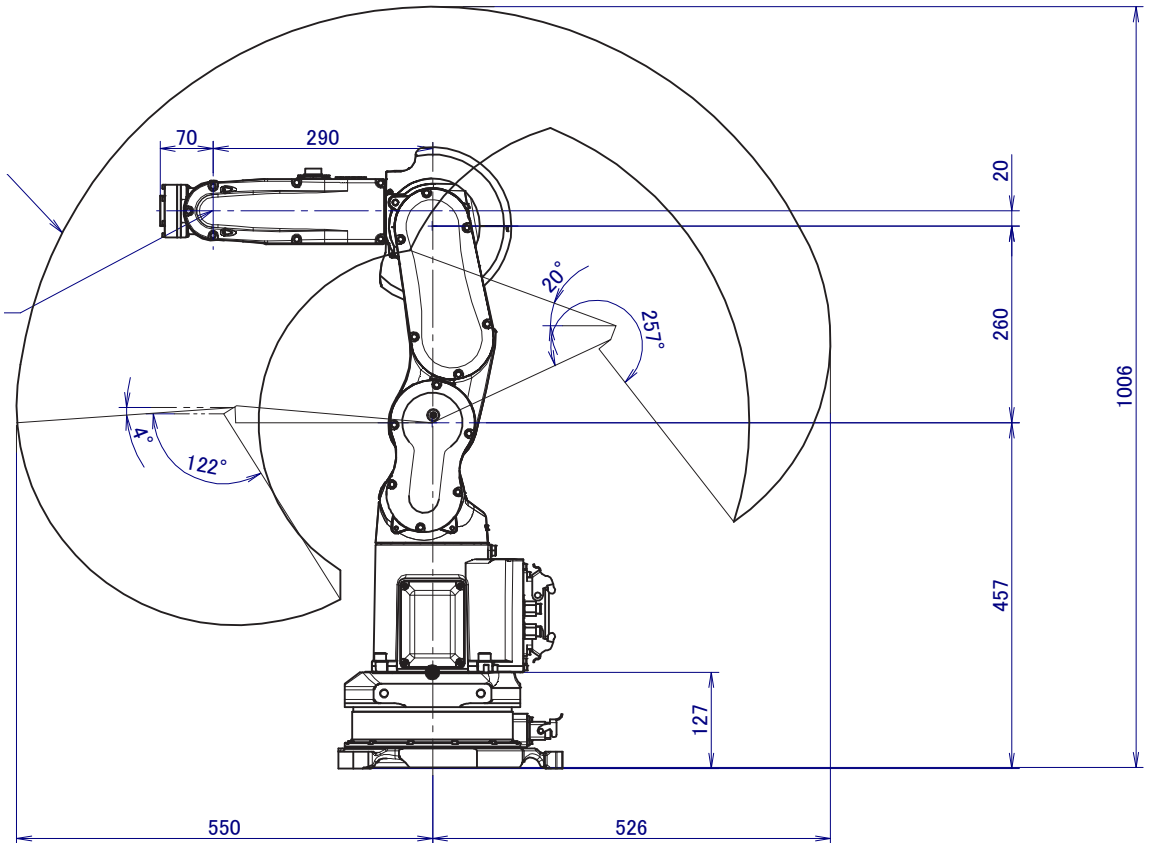
● standard ○ on request - not available \* max. cartesian speed 1000mm/sec \*\* Based on ISO9283 \*\*\*Option

CR-4iA Standard Model



Operating space of J5-axis rotation center

J5-axis rotation center



CR-4iA